



cyberelectronics commented 19 days ago • edited by PowerBroker2 ▾

@KoYoT77 I think we have similar issues.

Your data is there, after 7F.... bytes, but probable the parser stops after a few bytes.

One of my friends sent me a parser, which worked great for ~15seconds :) , after this the ESP32 module crashed (picture attached at the end, where you can see where is the issue, but I don't know how to fix it and he is busy now).

Here is the code for parsing:

```
void clearData() {
    dataFrame0 = "";
    dataFrame1 = "";
    dataFrame2 = "";
    dataFrame3 = "";
    dataFrame4 = "";
    dataFrame5 = "";
    dataFrame6 = "";
    dataFrame7 = "";
    dataFrame8 = "";
}

char* appendCharToCharArray(char* array, char c) {
    int len = strlen(array);

    char ret[len + 2];

    strcpy(ret, array);
    ret[len] = c;
    ret[len + 1] = '\0';

    return strdup(ret);
}

void addToFrame(int frame, char c) {
    switch (frame) {
        case 0:
            dataFrame0 = appendCharToCharArray(dataFrame0, c);
            break;
        case 1:
            dataFrame1 = appendCharToCharArray(dataFrame1, c);
            break;
        case 2:
            dataFrame2 = appendCharToCharArray(dataFrame2, c);
            break;
        case 3:
            dataFrame3 = appendCharToCharArray(dataFrame3, c);
            break;
        case 4:
            dataFrame4 = appendCharToCharArray(dataFrame4, c);
            break;
        case 5:
            dataFrame5 = appendCharToCharArray(dataFrame5, c);
            break;
    }
```

```
        case 6:
            dataFrame6 = appendCharToCharArray(dataFrame6, c);
            break;
        case 7:
            dataFrame7 = appendCharToCharArray(dataFrame7, c);
            break;
        case 8:
            dataFrame8 = appendCharToCharArray(dataFrame8, c);
            break;
    }
}

// get substring between m and n (excluding n)
char* substr(const char *src, int m, int n) {
    n += 1;
    int len = n - m;

    char *dest = (char*)malloc(sizeof(char) * (len + 1));

    for (int i = m; i < n && *(src + i) != '\0'; i++)
    {
        *dest = *(src + i);
        dest++;
    }

    *dest = '\0';

    return dest - len;
}

void parse(char *raw) {
    int frame = -1;

    int len = strlen(raw);

    for (int i = 0; i < len; i++) {

        if (raw[i + 1] == ':') { //start frame
            frame = (int) raw[i] - '0';
            continue;
        }

        if (raw[i] == ':') {
            continue;
        }

        if (frame == -1) {
            continue;
        }

        if (raw[i] == '>') {
            frame = -1;
            continue;
        }

        addToFrame(frame, raw[i]);
    }
}
```

```

}

int convertToInt(char *hexStr) {
    return (int)strtol(hexStr, NULL, 16);
}

```

And here is how to use it in the **loop()**, with some **delay/timer** (in my case, this will return/print battery voltage):

```

myELM327.sendCommand("AT SH 7E4");          // Set Header BMS (Battery Management System)

if (myELM327.queryPID("220101")) {          // BMS PID
    read_rawdata();

    BATTv = ((convertToInt(substr(dataFrame2, 4, 5)) << 8) + convertToInt(substr(dataFrame2, 6,
    DEBUG_PORT.print("Main Battery Voltage (V): ");
    DEBUG_PORT.println(BATTv);
    clearData();
}

```

Read_rawdata function looks like this (will print the rawdata coming from OBD, then will parse it):

```

void read_rawdata() {
    // move data from OBD to Rawdata array
    char rawData[myELM327.recBytes];
    int n = 0;

    DEBUG_PORT.print("Payload received: ");

    for (int i = 0; i < myELM327.recBytes; i++) {
        rawData[n++] = myELM327.payload[i];
        DEBUG_PORT.print(myELM327.payload[i]);
    }
    DEBUG_PORT.println();

    parse(rawData); // parse data received from OBD
}

```

Rawdata from OBD:

```

Payload received:
7F22127F22127F22127F22127F221203E0:620101FFF7E71:FF8A00000000832:00240ED71713133:141713000010C1
4:22C12800008B005:00450B0000434B6:000019A80000187:1200200EE70D018:7B0000000003E8

```

Parse(rawData), will look for dataframes, which begins with **0: 1: 2: 3:** etc... then I can select any byte in any dataframe:

Ex.:

```
Dataframe2 >>>>>>>>> 2:00240ED7171313
```

`convertToInt(substr(dataFrame2, 4, 5)) >>>>` will return a single byte on location 4 and 5 (from 0) in dataframe 2.

`convertToInt(substr(dataFrame2, 6, 7)) >>>>` will return a single byte on location 6 and 7 (from 0) in dataframe 2.

Result >>>

0E = 14;

D7 = 215;

Formula for Battery voltage = $(14 * 256 + 215) / 10.0 = 379.9V$

Now the problem is the parser will crash (possible memory leak) after 10-15seconds, until the crash, the parser works great.

Maybe @PowerBroker2 can help both of us, with this parser :) .

As I know we should not use `malloc()` at all (or use it with `free()`).

```

Exception Decoder
Guru Meditation Error: Core 1 panic'ed (LoadProhibited). Exception was unhandled.
Core 1 register dump:
PC      : 0x400014fd  PS      : 0x00060a30  A0      : 0x800d2fe9  A1      : 0x3ffcf1b0
A2      : 0x00000000  A3      : 0xffffffff  A4      : 0x000000ff  A5      : 0x00000f00
A6      : 0x00ff0000  A7      : 0xffff0000  A8      : 0x00000000  A9      : 0x3ffcf170
A10     : 0x00000000  A11     : 0x3ffcf1b0  A12     : 0x0000000b  A13     : 0x00000000
A14     : 0x00000000  A15     : 0x0000000a  SAR      : 0x0000001c  EXCCAUSE: 0x0000001c
EXCVADDR: 0x00000000  LEAR0  : 0x400014fd  LEAR1  : 0x4000150d  LCOUNT  : 0xffffffff

Backtrace: 0x400014fd:0x3ffcf1b0 0x400d2fe6:0x3ffcf1c0 0x400d3070:0x3ffcf1e0 0x400d30ed:0x3ffcf200 0x400d316c:0x3ffcf220 0x400d5142:0x3ffcf2b0 0x400d5669:0x3ffcf2d0 0x400f0c15:0x3ffcf2f0 0x40090035:0x3ffcf310

PC: 0x400014fd
EXCVADDR: 0x00000000

Decoding stack results
0x400d2fe6: appendCharToCharArray(char*, char) at D:\Ceges\GoogleHome\arduino-1.8.13\portable\sketchbook\ESP32_Konassist_OBD\PARSE.ino line 15
0x400d3070: addToFrame(int, char) at D:\Ceges\GoogleHome\arduino-1.8.13\portable\sketchbook\ESP32_Konassist_OBD\PARSE.ino line 53
0x400d30ed: parse(char*) at D:\Ceges\GoogleHome\arduino-1.8.13\portable\sketchbook\ESP32_Konassist_OBD\PARSE.ino line 101
0x400d316c: read_rawdata() at D:\Ceges\GoogleHome\arduino-1.8.13\portable\sketchbook\ESP32_Konassist_OBD\ESP32_Konassist_OBD.ino line 971
0x400d5142: read_data() at D:\Ceges\GoogleHome\arduino-1.8.13\portable\sketchbook\ESP32_Konassist_OBD\ESP32_Konassist_OBD.ino line 1193
0x400d5669: loop() at D:\Ceges\GoogleHome\arduino-1.8.13\portable\sketchbook\ESP32_Konassist_OBD\ESP32_Konassist_OBD.ino line 873
0x400f0c15: loopTask(void*) at D:\Ceges\GoogleHome\arduino-1.8.13\portable\packages\esp32\hardware\esp32\1.0.4\cores\esp32\main.cpp line 19
0x40090035: vPortTaskWrapper at /home/runner/work/esp32-arduino-lib-builder/esp32-arduino-lib-builder/esp-idf/components/freertos/port.c line 143
  
```

cyberelectronics commented 16 days ago • edited by PowerBroker2

Fortunately, Matthew, who wrote the SafeString library, helped me with this issue.

Just finished a live test, while charging the car for 50 minutes.

No reboot or WiFi and BT connection issues at all.

OBD BT queried once/sec and the datas (in multiple groups) was sent every 2 seconds to Blynk.

So here is the working parser for OBD protocol 6 with multiple dataframes (from 0: 1: 2: to 8:).

I hope this will help others (maybe @PowerBroker2 will add this to a new release)

Thanks guys!

```
#include "SafeString.h"
```

```

createSafeString(dataFrame0, 14); // will also add space for the terminating null =>15 sized
createSafeString(dataFrame1, 14);
createSafeString(dataFrame2, 14);
createSafeString(dataFrame3, 14);
createSafeString(dataFrame4, 14);
createSafeString(dataFrame5, 14);
createSafeString(dataFrame6, 14);
createSafeString(dataFrame7, 14);
createSafeString(dataFrame8, 14);
  
```

```
void clearData() {
    dataFrame0.clear();
    dataFrame1.clear();
    dataFrame2.clear();
    dataFrame3.clear();
    dataFrame4.clear();
    dataFrame5.clear();
    dataFrame6.clear();
    dataFrame7.clear();
    dataFrame8.clear();
}

void addToFrame(int frame, char c) {
    switch(frame) {
        case 0:
            dataFrame0 += c;
            break;
        case 1:
            dataFrame1 += c;
            break;
        case 2:
            dataFrame2 += c;
            break;
        case 3:
            dataFrame3 += c;
            break;
        case 4:
            dataFrame4 += c;
            break;
        case 5:
            dataFrame5 += c;
            break;
        case 6:
            dataFrame6 += c;
            break;
        case 7:
            dataFrame7 += c;
            break;
        case 8:
            dataFrame8 += c;
            break;
    }
}

void frameSubstr(SafeString& frame, int m, int n, SafeString& subStr) {
    frame.substring(subStr,m,n); // SafeString substring is inclusive m to n
}

int convertToInt(SafeString& dataFrame, size_t m, size_t n) {
    // define a local SafeString on the stack for this method
    createSafeString(hexSubString, 14); // allow for taking entire frame as a substring
    frameSubstr(dataFrame, m, n, hexSubString);
    return (int)strtol(hexSubString.c_str(), NULL, 16);
}

void parse(char *raw) {
    int frame = -1;
```

```

    int len = strlen(raw);

    for(int i=0; i<len; i++) {

        if(raw[i+1] == ':') { //start frame
            frame = (int) raw[i] - '0';
            continue;
        }

        if(raw[i] == ':') {
            continue;
        }

        if(frame == -1) {
            continue;
        }

        if(raw[i] == '>') {
            frame = -1;
            continue;
        }

        addToFrame(frame, raw[i]);
    }
}

void read_rawdata(){
    // move data from OBD to Rawdata array
    char rawData[myELM327.recBytes];
    int n = 0;

    DEBUG_PORT.print("Payload received: ");

    for (int i=0; i<myELM327.recBytes; i++) {
        rawData[n++] = myELM327.payload[i];
        DEBUG_PORT.print(myELM327.payload[i]);
    }

    DEBUG_PORT.println();

    parse(rawData); // parse data received from OBD

}

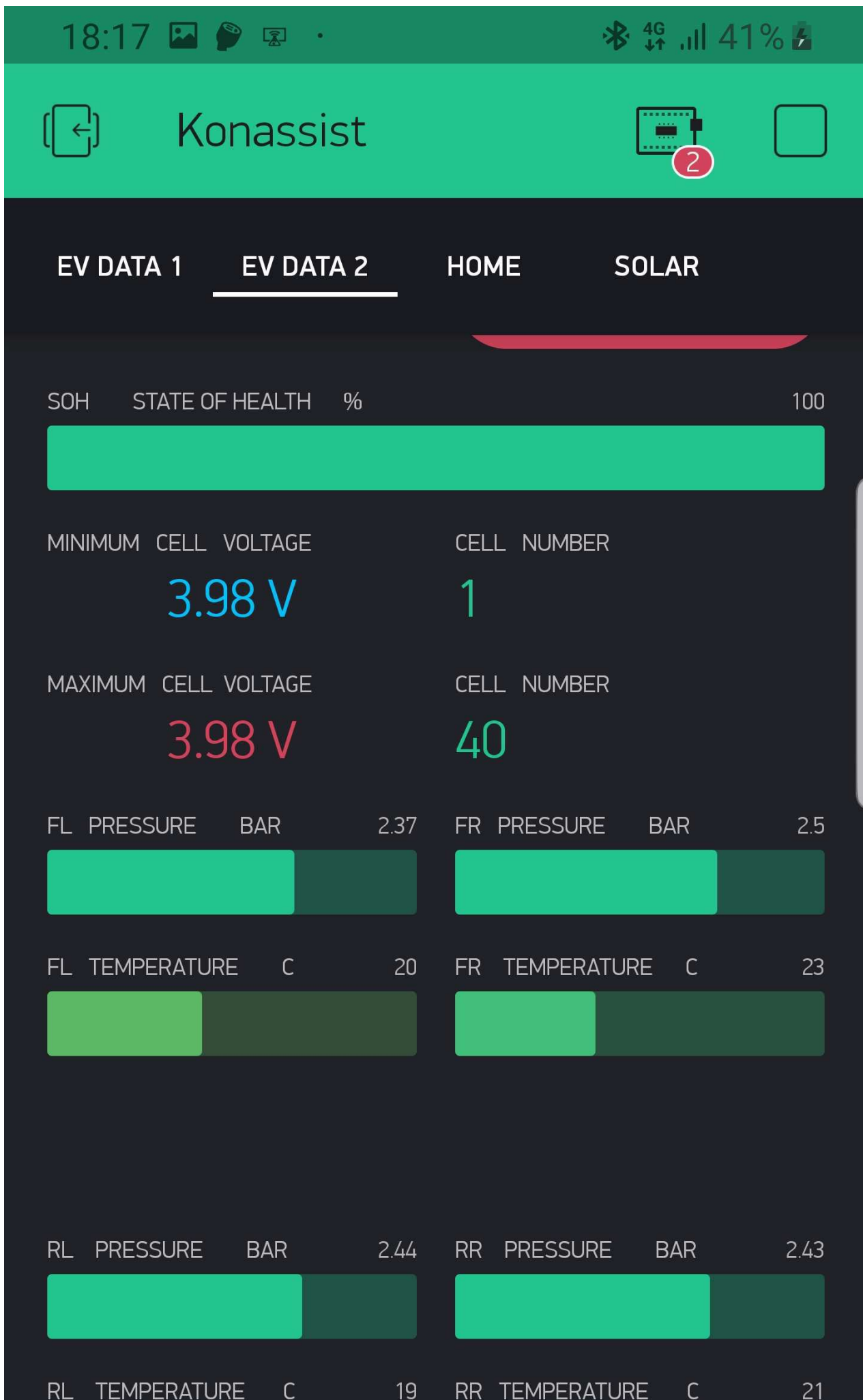
// loop
void loop(){
    // insert timer/delay (ex. 1sec)
    ...
    myELM327.sendCommand("AT SH 7E4"); // Set Header BMS

    if (myELM327.queryPID("220101")) { // BMS PID = hex 22 0101 => dec 34, 257

        read_rawdata();
        BATTv = ((convertToInt(dataFrame2, 4, 5)<<8) + convertToInt(dataFrame2, 6, 7)<<8) / 1000;
        DEBUG_PORT.print("Main Battery Voltage (V): ");
        DEBUG_PORT.println(BATTv);
        clearData();
    }
}

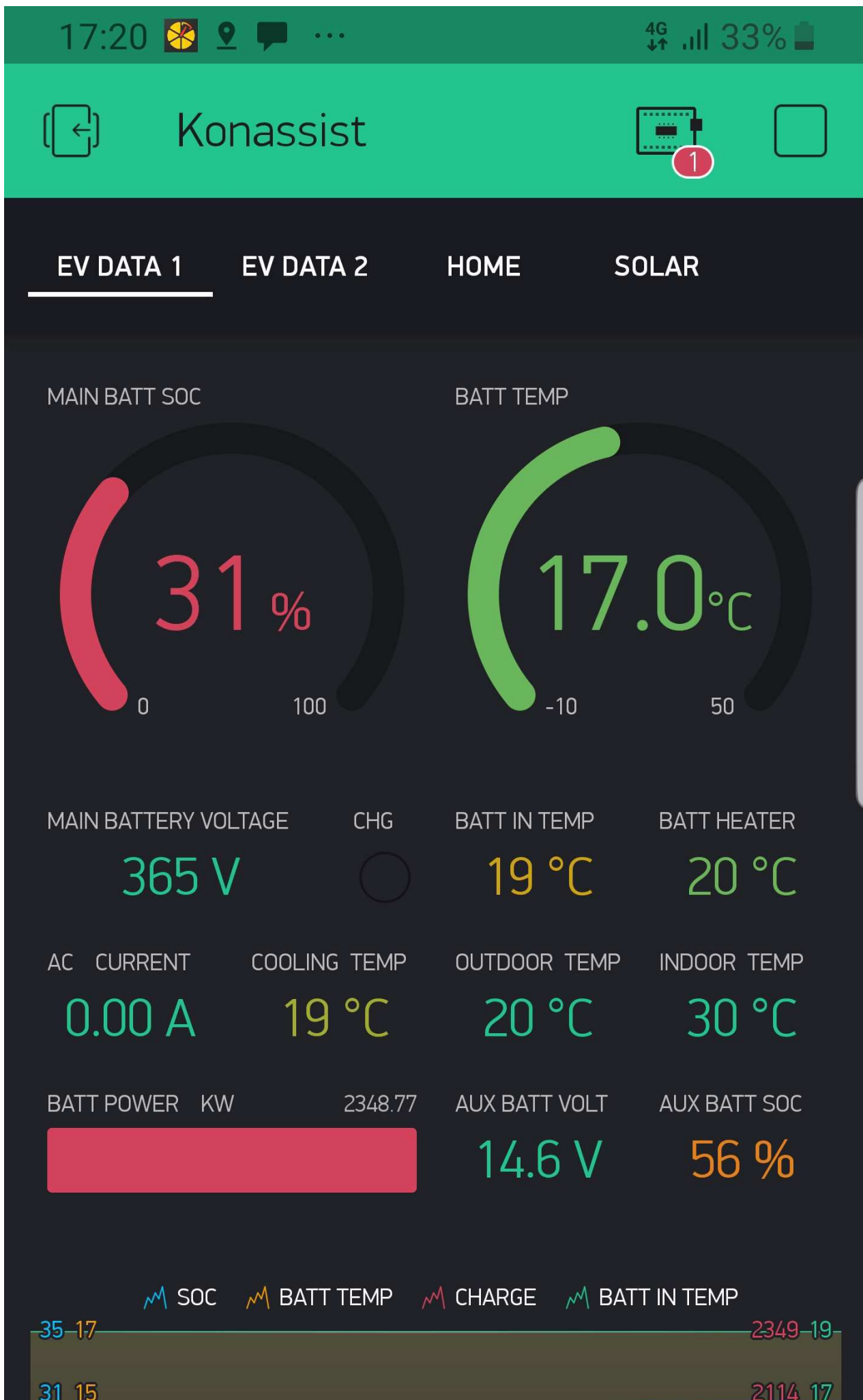
```

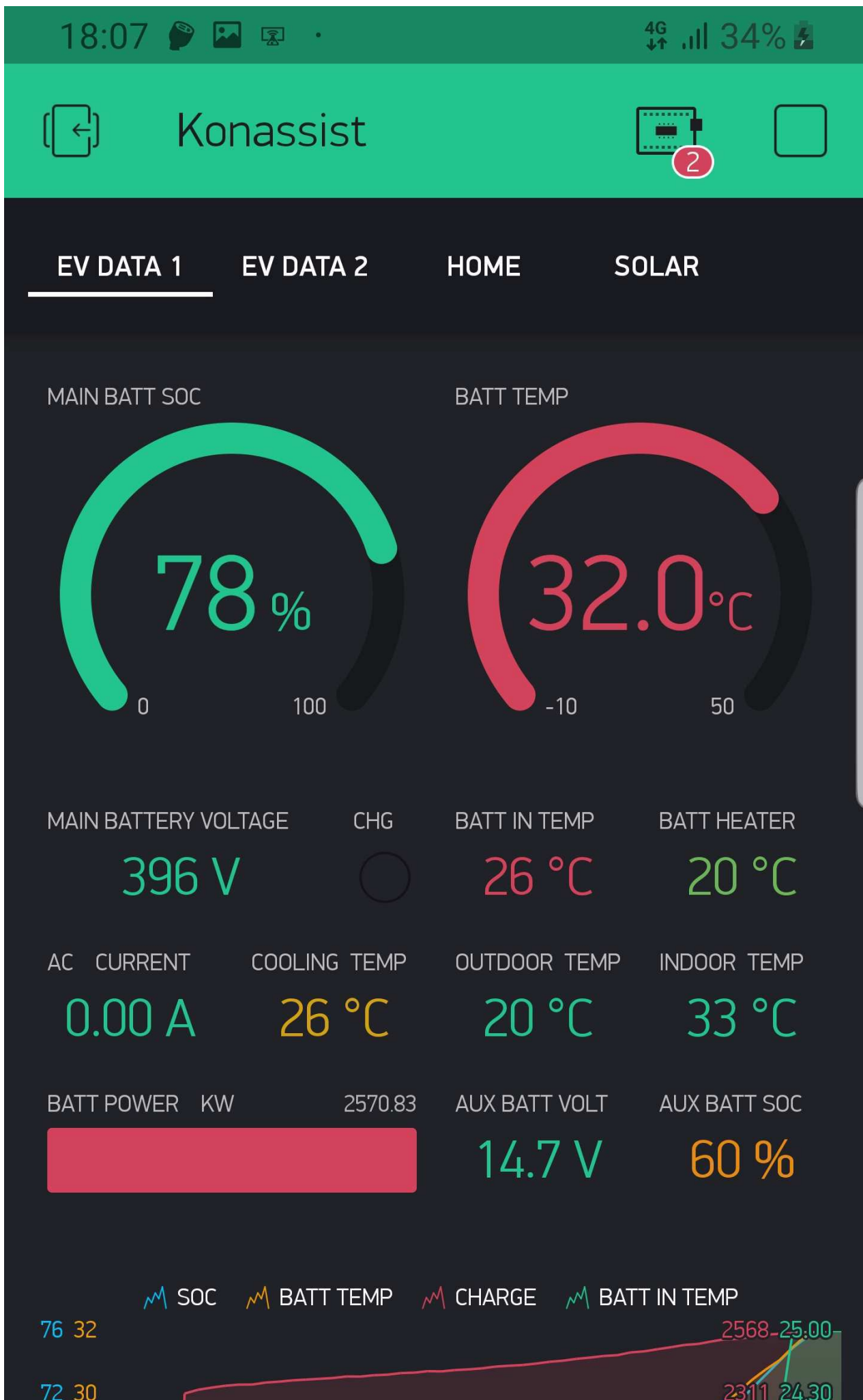
```
}  
  
}
```













PowerBroker2 commented 15 days ago

Owner

This is dope! I'll take a closer look later and see if/how I can incorporate it.

However, @cyberelectronics, feel free to fork and PR if you want to do it yourself. Either way, thanks!



EV DATA 1

EV DATA 2

HOME

SOLAR



cyberelectronics commented 15 days ago

Thanks, but I don't know how to use github :D .

Also if you can, please add/modify the code for other cases, where the dataframe delimiters are missing (no 0: , when all datas are in a single frame package) like in @KoYoT77 example.

Ex. PID >223275

Response: 62 32 75 4E

Skip any 7F... bytes at the beginning sent by OBD adapter, and Search/Compare for the first byte of PID 22hex + 40hex = 623275hex >>> 4E..... hex data bytes (dataframe).



OPERATING TIME

TRIP DISTANCE



KoYoT77 commented 15 days ago

Gents,

With Jaukb's help - our sketch works.

The issue was in this line of code:

```
sprintf(command, SET_HEADER, "7E0");
```

Elmduino.h const as below:

```
const char * const SET_HEADER = "AT SH"; // OBD
```

has been edited to this line

```
const char * const SET_HEADER = "AT SH %s"; // OBD
```

finally we have received proper data, same as in the App DPM Monitor.

Thanks to both of you and Jakub too!



1



4.00 V

90

MAXIMUM CELL VOLTAGE

CELL NUMBER

4.00 V

45

FL PRESSURE

BAR

0

FR PRESSURE

BAR

0

question



No milestone

Linked pull requests

Successfully merging a pull request may close this issue.

None yet

4 participants

